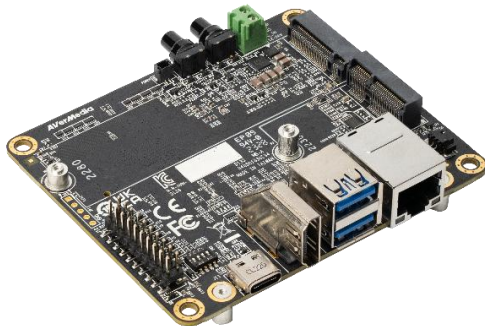


AVerMedia D133 series

Applies to NVIDIA® Jetson Orin™ NX/ Orin™ NANO Module



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Preface

Disclaimer

The information contained in this user manual, including but not limited to any product specification is subject to change without notice. AVerMedia assumes no liability for any damages incurred directly or indirectly from any technical or typographical errors or omissions contained herein or for discrepancies between the product and the user manual.

Technical Support

If you experience the difficulty after reading this manual and/or using the product, please contact the reseller from which you purchased the product. In most cases, the reseller can help you with the product installation and the difficulty you encountered.

In case the reseller is not able to resolve your problem, our highly capable global technical support team can certainly assist you. Our technical support section is available 24 hours a day and 7 days a week through our website, with the click [here](#). For more contact information, you may find it in the section of AVerMedia Global Offices.

Contact Enquiry

For more information of our products, pricing, and order placement, please fill in our inquiry form [here](#), we will contact you within 24 hours.

Download User Manual

Please click the link [here](#) to download the file of this user manual from AVerMedia website.

Revision History

Revision	Date	Updates
Version 1.0	Oct. 11, 2023	1 st Released
Version 1.1	Jan. 19, 2024	Update D133OXB power consumption
Version 1.2	Mar. 05, 2024	Update input power range
Version 1.3	May 13, 2024	Revise the location of Recovery button and Power button.
Version 1.4	July 16, 2024	Update WDT function's definition.
Version 1.5	June 30, 2025	Chang from raspberry pi camera v2/v3 to raspberry pi imx219 & imx477 (V2)
Version 1.6	July 11, 2025	Update Product Specifications on P.9~11 Update Power Cord Spec & Warning message on P.43
Version 1.7	Sep. 15, 2025	Modify Product Warranty

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Product Warranty

Please refer to [Support | Warranty And Rma Services | AVerMedia](#)

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ESD Warning

Electronic components and circuits are sensitive to Electrostatic Discharge (ESD). When handling any circuit board assemblies including AVerMedia AVerMedia products, it is highly recommended that ESD safety precautions can be observed. ESD safe best practices can include, but are not limited to the following ones.

1. Leave the circuit board in the antistatic package until it is ready to be installed.
2. Use a grounded wrist strap when handling the circuit board. At a minimum, you need to touch a grounded metal object to dissipate any static charge, which may be present on you.
3. Avoid handling the circuit board in the carpeted areas.
4. Handle the board by the edges and avoid the contact  with the components.
5. Only handle the circuit boards in ESD safe areas, which may include ESD floor and/or table mats, wrist strap stations, and ESD safe lab coats.

Safety Precaution:

1. All cautions and warnings on the device should be noted.
2. For safety consideration, do NOT open the device if not a qualified service staff.
3. Place the device on a solid surface during installation to prevent falls.
4. Keep the device away from humidity.
5. Do NOT leave this device in an un-controlled environment with temperatures beyond the device's permitted storage temperature to avoid damage.
6. All adaptors and cables supplied by AVerMedia are verified. Do NOT use any others not supplied by AVerMedia to avoid any malfunction or fires.
7. Make sure the power source matches the power rating of the device.
8. Place the power cord where people cannot step on it. Do not put anything on the power cord.
9. Always completely disconnect the power while the device is not usage or idle for a long time.

10. Disconnect the device from any AC supply before cleaning. While cleaning, use a damp cloth instead of liquid or spray detergents.
11. Make sure the device is installed near a power outlet and easy for accessible.
12. Do not cover the openings on the device to ensure optimal heat dissipation.
13. Watch out the heatsink or heat spreader of the device when the system is running.
14. Never pour any liquid into the openings. This could cause fire or electric shock.
15. The static electricity should be noted while installing any internal components. Consider to use a grounding wrist strap and put all electronic parts in static-shielded containers.

If the following situations occur, please contact our service personnel:

- (1) The device is dropped or damaged
- (2) Damaged power cord or plug
- (3) Exposure to moisture
- (4) Liquid intrusion into the device
- (5) Any obvious signs of damage displayed on the device
- (6) Device is not working as expected or in a manner as described in this manual

1.0 Introduction

AVerMedia D133/D133ON/D133ONB is a fully featured carrier board/engineering kit/box PC designed for NVIDIA® Jetson Orin Nano modules. AVerMedia provides access to a wide range of latest interfaces on NVIDIA® Jetson Orin Nano modules.

D133/D133ON/D133ONB provide HDMI video output , two USB 3.2 ports, one GbE RJ-45 port, 20-pin expansion header, and one USB 2.0 type C port for recovery.

Operating with NVIDIA® Jetson Orin Nano modules and the rich I/O functions, AVerMedia D133/D133ON/D133ONB is the perfect choice in building a compact, high performance AI edge computing platform for the intelligent video analytics applications.

1.1 Product Specifications

Model	D133
Type	Carrier board
NVIDIA GPU SoC Module Compatibility	NVIDIA® Jetson Orin NANO-8G module NVIDIA® Jetson Orin NX-16G/8G module
Networking	1x GbE RJ-45 1x M.2. key E 2230 for Wi-Fi
Display Output	1x HDMI 4Kp30 for Orin Nano 1x HDMI 4Kp60 for Orin NX (TBD)
Temperature	Operating temperature -25°C~85°C Storage temperature -40°C ~ 85°C Relative humidity 40 °C @ 95%, Non-Condensing
MIPI Camera Inputs	2x 4 lane MIPI CSI-2, 22 pin FPC 0.5mm Pitch Connector
USB	1 x USB 2.0 type C for recovery 2 x USB 3.0 Type-A
Storage*	1x M.2. key M 2280 for NVMe
Expansion Header	20 pins: 2x I2C, 1x UART, 9x GPIOs
Power requirement	3.5mm Screw Terminal; 12V/5A, 9V~24V is recommended.
Power adapter/Power Cord	12V/5A adapter and US/JP/EU/UK/TW/AU/CN power cord (3-pin power cord, optional) US/JP/EU/UK/TW/AU/CN (3-pin power cord) For JP: Adding a 2-pin power cord with a ground wire. *Warning* Indicating that the ground (GND) must be properly connected when plugging in the adapter
Fan Module	Fan solution (optional)
Buttons	Power and Recovery
RTC Battery	Support RTC battery and Battery Life Monitoring by MCU
PCB/Electronics Mechanical Info	W: 90mm x L: 76mm x H: 27.34mm Weight: 70g
Certifications	CE, FCC, VCCI, KC

Model	D133OX/ON
Type	Engineering kit
NVIDIA GPU SoC Module Compatibility	NVIDIA® Jetson Orin NANO-8G module NVIDIA® Jetson Orin NX-16G/8G module
Networking	1 x GbE RJ-45 1 x M.2. key E 2230 for wifi
Display Output	1x HDMI 4Kp30 for Orin Nano 1x HDMI 4Kp60 for Orin NX (TBD)
Temperature	Operating temperature -25°C~60°C Storage temperature -40°C ~ 85°C Relative humidity 40 °C @ 95%, Non-Condensing
MIPI Camera Inputs	2 x 4 lane MIPI CSI-2, 22 pin FPC 0.5mm Pitch
USB	1 x USB 2.0 type C for recovery 2 x USB 3.0 Type-A
Storage*	1x M.2. key M 2280 for NVMe (256G SSD installed)
Expansion Header	20 pins: 2x I2C, 1x UART, 9x GPIOs
Power requirement	3.5mm Screw Terminal; 12V/5A, 9V~24V is recommended.
Power adapter/Power Cord	12V/5A adapter and US/JP/EU/UK/TW/AU/CN power cord (3-pin power cord, optional) For JP: Adding a 2-pin power cord with a ground wire. *Warning* Indicating that the ground (GND) must be properly connected when plugging in the adapter
Fan Module	Fan solution
Buttons	Power and Recovery
RTC Battery	Support RTC battery and Battery Life Monitoring by MCU
Dimension/Weight	W: 93mm x L: 81.2mm x H: 57mm Weight: 500g
Certifications	CE, FCC, VCCI, KC

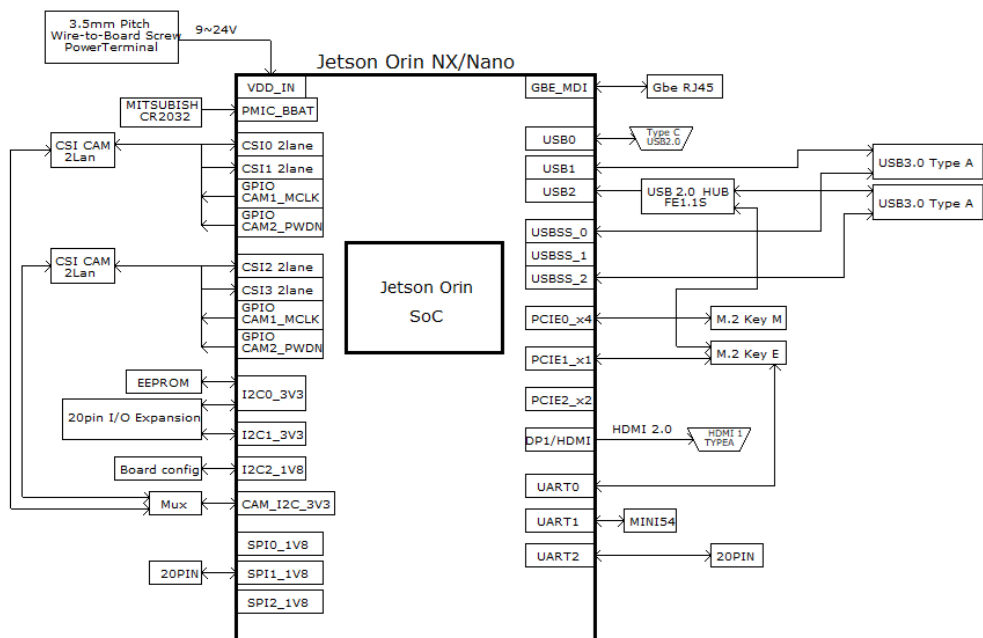
Model	D133OXB/ONB
Type	Box PC
NVIDIA GPU SoC Module Compatibility	NVIDIA® Jetson Orin NANO-8G module NVIDIA® Jetson Orin NX -16G/8G module
Networking	1 x GbE RJ-45 1 x M.2. key E 2230 for wifi
Display Output	1x HDMI 4Kp30 for Orin Nano 1x HDMI 4Kp60 for Orin NX
Temperature	Operating temperature -25°C~60°C Storage temperature -40°C ~ 85°C Relative humidity 40 °C @ 95%, Non-Condensing
MIPI Camera Inputs	2 x 4 lane MIPI CSI-2, 22 pin FPC 0.5mm Pitch
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Fan Module	Fan solution
Buttons	Power and Recovery
RTC Battery	Support RTC battery and Battery Life Monitoring by MCU
Dimension/Weight	W: 93mm x L: 81.2mm x H: 74.4mm Weight: 500g
Certifications	CE, FCC, VCCI, KC

1.2 Option Accessory

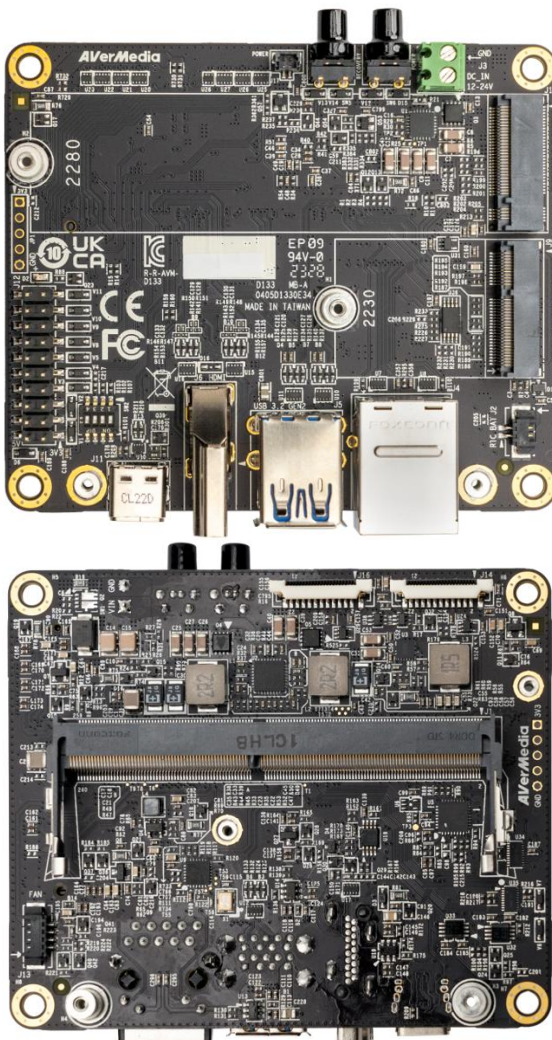
Item	D133 series
NVIDIA® Jetson	NVIDIA® Jetson Orin™ NX / Orin™ Nano for D133
Power adapter/ Power Cord	12V/5A adapter and US/JP/EU/UK/TW/AU/CN power cord (optional)
MIPI Camera (internal I/O)	● For 22 pin MIPI connector 1. raspberry pi imx219 & imx477 (V2) 2. Manufacturer: APPRO.PHO ■ B-04: IMX179(8M)MIPI, 1080P(30fps)

2.0 Product Overview

2.1 Block Diagram



2.2 Front View and Back View of Carrier board



2.3 Front View and Three -Quarter View of BoxPC

Left view



Right view



Top view



Front View



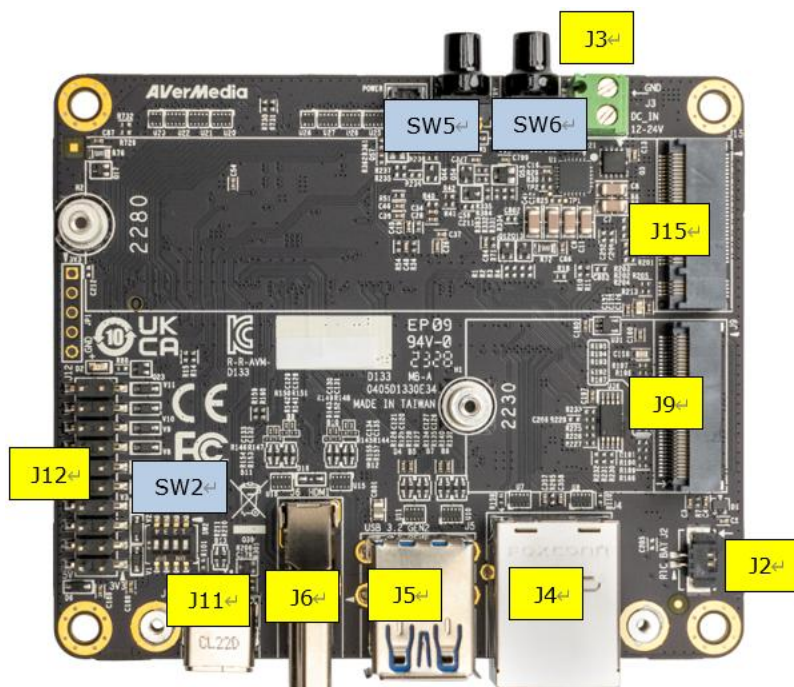
Back view



2.3 Connector Summary

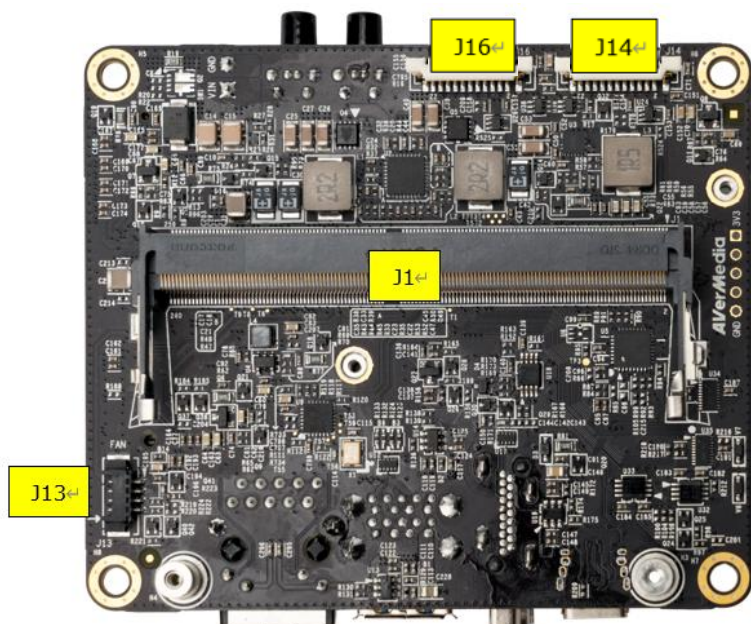
Front View Interface

J2	External RTC Battery wafer
J3	DC power jack
J4	Gigabit Ethernet Connector w/LEDs
J5	USB 3.0 Gen1 Dual Port Type A Connector
J6	HDMI Type-A Vertical Side Connector with lock (Female)
J9	M.2 E-Key Socket
J11	USB type C
J12	20-pin Expansion
J15	M.2 M-Key Socket
SW2	DIP switch
SW5	Recovery Button w/LEDs
SW6	Power Button w/LEDs



Back View Interface

J1	SO-DIMM 260-pin 90° SMD Socket(H-9.2mm) for Jetson Orin™ NX/ Orin™ Nano SOM
J13	Fan Wafer
J14	FPC connector for 4-lane MIPI CSI-2
J16	FPC connector for 4-lane MIPI CSI-2



3.0 Feature Description

3.1 Jetson module Connector

Function	Provide connection with NVIDIA® Jetson Orin™ NX /Orin Nano module	
Location	J1	
Type Description	SOCKET_DDR4 SO-DIMM_260PIN_90°	
Manufacturer and Part Number	Foxconn ASAA826-EASB0-7H	
Mating Connector	NVIDIA® Jetson Orin™ NX/Orin Nano	
Pinout	Please refer to NVIDIA Jetson System-on-Module datasheet for pinout details.	
Remarks	https://developer.nvidia.com/embedded/downloads	

3.2 RTC Battery Connector

Function	RTC battery for module							
Location	J2							
Type Description	WAFER_1*2PIN_1.25 mm_90°_SMD							
Manufacturer and Part Number	宏致_50271-00201-001							
Mating Connector	Molex 51021-8602							
Pinout	<table><tr><th>Pin #</th><th>Description</th></tr><tr><td>PIN1</td><td>GND</td></tr><tr><td>PIN2</td><td>3V Power</td></tr></table>			Pin #	Description	PIN1	GND	PIN2
Pin #	Description							
PIN1	GND							
PIN2	3V Power							
Remarks	RTC Battery: KTS BCR2032TH5.5VM1MB							

3.3 Power Supply Connector

DC Power Supply Connector				
Function	Power Supply			
Location	J3			
Type Description	Socket_Terminal Block_1*2PIN_90°			
Manufacturer and Part Number	DECA MB332-350M02			
Mating Connector	DC 5.5 x 2.5 mm Power cable			
Pinout	PIN#	Description	Color	
	#1	9-24V	White	
	#2	GND	Black	
Remarks	None			

3.4 Gigabit Ethernet Connector

RJ45 Gigabit Ethernet Connector			
Function	1Gb single-port Ethernet connector, used to connect to the host system.		
Location	J4		
Type Description	RJ45 8P8C single-port with LED		
Manufacturer and Part Number	鴻海_JFM38013-0L03-4F		
Mating Connector	Any RJ45 plug with Cat5, Cat5e, Cat6 type cabling.		
Pinout	Comply with Ethernet standards.		
Remarks	NA		

3.5 USB 3.2 Gen2 Type-A Connector #1 and #2

Function	USB 3.2 Gne2 Type-A connector #1 & #2	
Location	J5	
Type Description	Dual-port USB 3.2 Type-A female connector	
Manufacturer	冠泰, CU3B-AFR15U-096H	

and Part Number		
Mating Connector	Any USB 3.2 standard Type-A interface cable or device.	
Pinout	Please refer to USB 3.2 standard.	
Remarks	None	

3.6 HDMI OUTPUT

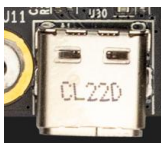
Function	HDMI output connector	
Location	J6	
Type Description	HDMI Type-A female connector	
Manufacturer and Part Number	捷湧 EDL, HM-FVD480B	
Mating Connector	Any HDMI standard Type-A interface cable or device.	
Pinout	Please refer to HDMI standard.	
Remarks	None	

3.7 M.2 E key 2230

Function	M.2 E key	
Location	J9	
Type Description	SOCKET_M.2-KEY E_75PIN_90°_SMD	
Manufacturer and Part Number	宏致_ACES 51748-07502-005_P0.5 mm-H8.5 mm	
Mating Connector	Any M.2 E key 2230 card standard interface device.	
Pinout	None	

3.8 USB type C Connector

USB type C Connector

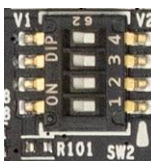
Function	BSP Installation as recovery mode	
Location	J11	
Type Description	JACK_USB_C TYPE(F)_90°_PIP-L1.45 mm	
Manufacturer and Part Number	宏致 ACES, 57988-0240D-001	
Mating Connector	Any USB type C standard interface cable	
PIN OUT	Please refer to USB type C standard.	

3.9 M.2 M key 2280

Function	M.2 M key
Location	J15
Type Description	SOCKET_M.2-KEY M_75PIN_90°_SMD
Manufacturer and Part Number	宏致_ACES 51757-0750C-012_P0.5 mm-H5.5 mm
Mating Connector	Any M.2 M key 2280 card standard interface device.
Pinout	Please refer to M.2 M key card standard for the pinout details.
Remarks	None



3.10 Optional Function Selection

Function	Fan PWM controller/Auto Power on																						
Location	SW2																						
Type Description	4 SPST DIP switch																						
Manufacturer and Part Number	DIPTRONICS IN OFF-SWITCHING 0.025A/24VDC																						
Pinout	<table><thead><tr><th>Position No.</th><th>Position Description</th><th>Switch ON</th><th>Switch OFF</th></tr></thead><tbody><tr><td>1 (SW1)</td><td>NA</td><td>NA</td><td>NA</td></tr><tr><td>2 (SW2)</td><td>WDT function</td><td>WDT disable</td><td>WDT enable</td></tr><tr><td>3 (SW3)</td><td>Power-Up / Start-up Control</td><td>"ATX Mode" - Power Button Press Required</td><td>"AT Mode" - Automatic Start-up Enabled</td></tr><tr><td>4 (SW4)</td><td>PWM Fan Control</td><td>FAN Always ON</td><td>FAN PWM Enabled (SW Controlled)</td></tr></tbody></table>			Position No.	Position Description	Switch ON	Switch OFF	1 (SW1)	NA	NA	NA	2 (SW2)	WDT function	WDT disable	WDT enable	3 (SW3)	Power-Up / Start-up Control	"ATX Mode" - Power Button Press Required	"AT Mode" - Automatic Start-up Enabled	4 (SW4)	PWM Fan Control	FAN Always ON	FAN PWM Enabled (SW Controlled)
Position No.	Position Description	Switch ON	Switch OFF																				
1 (SW1)	NA	NA	NA																				
2 (SW2)	WDT function	WDT disable	WDT enable																				
3 (SW3)	Power-Up / Start-up Control	"ATX Mode" - Power Button Press Required	"AT Mode" - Automatic Start-up Enabled																				
4 (SW4)	PWM Fan Control	FAN Always ON	FAN PWM Enabled (SW Controlled)																				
Remark	Default SW2 all OFF																						

3.11 Power Button

Function	Power button	 
Location	SW6	
Type Description	Button	
Manufacturer and Part Number	冠泰Champway, LS67AK-NBR-A-R2KA9	
Pinout	N/A	
Remark	None	

3.12 Recovery Button

Function	Recovery button	 
Location	SW5	
Type Description	Button	
Manufacturer and Part Number	冠泰Champway, LS67AK-NBR-A-R2KA9	
Pinout	N/A	
Remark	None	

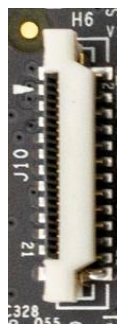
3.13 20-Pin GPIO expansion

Function	General-purpose input/output	
Location	J12	
Type Description	2x I2C, 1x UART, 9x GPIOs	
Manufacturer and Part Number	光榮:PHPME006-100ARRH	
Mating Connector	20-Pin GPIO expansion	

Pinout	Address	Pin Name	20-Pin Index (Devkit Index)		Pin Name	Address
		+3V3	1	2	+5V	
		GND	3	4	GND	
	/dev/i2c-7	I2C1_SDA	5	6	UART2_TXD_3V3	/dev/ttyTCU0 (Debug Console)
		I2C1_SCL	7	8	UART2_RXD_3V3	
	/dev/i2c-1	I2C0_SDA	9	10	GND	
		I2C0_SCL	11	12	SPI1_SCK	gpio(470)
	gpio(398)	I2S0_SCLK	13	14	SPI1_MISO	gpio(471)
	gpio(399)	I2S0_DOUT	15	16	SPI1_MOSI	gpio(472)
	gpio(400)	I2S0_DIN	17	18	SPI1_CS0	gpio(473)
	gpio(401)	I2S0_FS	19	20	SPI1_CS1	gpio(474)

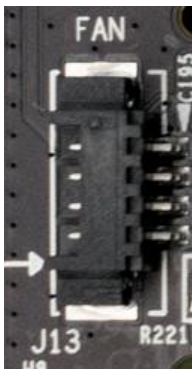
3.14 MIPI CSI-2 DPHY Lanes

Function	MIPI camera module connector			
Location	J14 , J16			
Type Description	WAFER_22PIN_0.5 mm_180°			
Manufacturer and Part Number	宏致_ACES, 50554-02241-003 0.5mm ZIF FPC CONN. SMT S/T TYPE			
Mating Connector	4 Lane MIPI CSI-2 camera connector (22Pin)			
Pinout	J14			
	Description	22-pin Index		Description
	+3V3_MIPI	Pin1	Pin2	CAM0_I2C_SDA
	CAM0_I2C_SCL	Pin3	Pin4	GND
	CAM0_MCLK	Pin5	Pin6	CAM0_PWDN_LS



	GND	Pin7	Pin8	CSI1_D1_P
	CSI1_D1_N	Pin9	Pin10	GND
	CSI1_D0_P	Pin11	Pin12	CSI1_D0_N
	GND	Pin13	Pin14	CSI0_CLK_P
	CSI0_CLK_N	Pin15	Pin16	GND
	CSI0_D1_P	Pin17	Pin18	CSI0_D1_N
	GND	Pin19	Pin20	CSI0_D0_P
	CSI0_D0_N	Pin21	Pin22	GND
J16				
	Description	22-pin Index		Description
	+3V3_MIP1	Pin1	Pin2	CAM1_I2C_SDA
	CAM1_I2C_SCL	Pin3	Pin4	GND
	CAM1_MCLK	Pin5	Pin6	CAM1_PWDN_LS
	GND	Pin7	Pin8	CSI3_D1_P
	CSI3_D1_N	Pin9	Pin10	GND
	CSI3_D0_P	Pin11	Pin12	CSI3_D0_N
	GND	Pin13	Pin14	CSI2_CLK_P
	CSI2_CLK_N	Pin15	Pin16	GND
	CSI2_D1_P	Pin17	Pin18	CSI2_D1_N
	GND	Pin19	Pin20	CSI2_D0_P
	CSI2_D0_N	Pin21	Pin22	GND

3.15 Fan Power connector

Function	Fan Power Connector			
Location	J13			
Type Description	WAFER_1*4PIN_1.25 mm_90°			
Manufacturer and Part Number	ACES 50271-0040N-001_BLACK			
Mating Connector	ACES 50276-004H0H0-001			
Pinout	Pin #	Description		
	PIN 1	GND		
	PIN 2	+5V Power		
	PIN 3	FAN_TACH		
	PIN 4	FAN_PWM		
Remarks	None			

3.16 Other Switches and Jumpers

Other switches and jumpers listed on the boards but not mentioned in this manual are reserved for the internal use by AVerMedia. They are not open to the client application.

4.0 Installation

1. Check and ensure all the external system power supplies are turned off.
2. Install the Micro USB2.0 cable to Jetson platform connector.
3. Press and hold on the Recover button.
4. Connect the power cord to the box PC.

4.1 BSP Setup Instructions

BSP (board support package) file: D133ON-R2.0.*.tar.gz for D133ON

If you want to get the BSP download link, Please contact with AVerMedia FAE.

Default login username/password of the BSP is nvidia/nvidia

If you have difficulties to access the BSP download link, please visit AVerMedia website at <https://www.avermedia.com/professional/download>, or contact technical support at https://www.avermedia.com/professional/technical_support or e-mail us at cusupport@avermedia.com for further assistance.

BSP Installation steps for NVIDIA Jetson board: (Important Note: Please backup your personal files before re-flashing BSP)

After you download the BSP file and put the file in a Linux PC, please refer to the steps below to re-flash BSP.

1. Let the JETSON Orin NX initiate recovery mode.

You have to keep pressing “Recovery” button and then power on the NVIDIA Jetson board to initiate recovery mode.

When connecting a NVIDIA Jetson board to a Linux PC via a MicroUSB to USB cable, you can check kernel messages with ‘dmesg’ command in the Linux PC.

Once you see these messages in the kernel messages, this means that the NVIDIA Jetson board is in the recovery mode.

```
[24685.229129] usb 1-7: Product: APX
```

```
[24685.229132] usb 1-7: Manufacturer: NVIDIA Corp
```

2. Using the commands below in the Linux PC to start re-flashing BSP.

```
$ sudo tar zxvf D133ON-R2.*.tar.gz
(file: D133ON-R2.*.tar.gz for D133ONB)
$ cd JetPack_*/Linux_for_Tegra
$ sudo ./setup.sh
$ sudo ./install.sh
```

The BSP is support flash to default nvme ssd or external USB dungle.

You can select whitch one you want to flash after launching the install script.

Note: sudo is required to re-flash the BSP..

5.0 Software

This section describes BSP's features for D133ONB

1. Support optional M.2 WI-FI/Bluetooth modules (Intel® Wireless-AC 9260), the manager UI of AC9260 WiFi/Bluetooth is located on the upper-right corner of Ubuntu desktop. It can be also controlled by nmcli/hcitol in command line.
2. Support SD slot (D133ON is not support SD card slot.)
3. Power Mode
Power mode can be modified by the UI on the upper-right corner of Ubuntu or the following commands.

```
# get current power mode
$ sudo nvpmodel -q
# setup power mode
# where <x> is power mode number, please refer to
https://docs.nvidia.com/jetson/archives/r35.2.1/DeveloperGuide/index.html#page/Tegra%20Linux%20Driver%20Package%20Development%20Guide/clock\_power\_setup.html for more information
$ sudo nvpmodel -m <x>
```

* Current default power mode:

D133ON: MODE 15W DESKTOP (2)

4. RTC Battery
The following command can get RTC battery voltage.

```
$ sudo avt_tool -a | grep -oP "AIN5.*[K[^\]]*"
```

5. Fan Speed

The following commands can get PWM fan information.

```
# get Fan RPM value
$ cat /sys/devices/platform/gpio_tachometer/hwmon/hwmon1/gpiotach_rpm
```

6. MIPI CSI Camera

There are 2x 2-lane and 1x 4-lane MIPI CSI camera supported on D133ONB, for current supported products type are listing as below:

* IMX219 (2-lane)

* IMX477 (2-lane): IMX477 requires a hardware modification in order to work with Jetson Platforms. Please refer to

https://developer.ridgerun.com/wiki/index.php/Raspberry_Pi_HQ_camera_IMX477_Linux_driver_for_Jetson#Compatibility_with_NVIDIA.C2.AEJetson.E2.84.A2_Platforms

* IMX179 (2-lane)

* IMX290 (2-lane)

* IMX290ISP (2-lane)

Test Command:

> Raspberry pi v2 :

* Please follow the settings below first:

1. Set the power mode to maximize at 25W.

2. Follow the settings in the Release Notes, and maximize the ISP & VI clock.

No	width	height	framerate
0	3264	2464	21
1	3264	1848	28
2	1920	1080	30
3	1640	1232	30
4	1280	720	60

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)3280, height=(int)2464, format=(string)NV12, framerate=(fraction)21/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)3280, height=(int)1848, format=(string)NV12, framerate=(fraction)28/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)1920, height=(int)1080, format=(string)NV12, framerate=(fraction)30/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)1640, height=(int)1232, format=(string)NV12, framerate=(fraction)30/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)1280, height=(int)720, format=(string)NV12, framerate=(fraction)60/1' ! queue ! nvvidconv ! xvimagesink -e
```

Multiple:

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)3264, height=(int)2464, format=(string)NV12, framerate=(fraction)21/1' ! queue ! nvvidconv ! xvimagesink -e & gst-launch-1.0 nvarguscamerasrc sensor-id=1 sensor-mode=0 ! 'video/x-raw(memory:NVMM), width=(int)3264, height=(int)2464, format=(string)NV12, framerate=(fraction)21/1' ! nvvidconv ! xvimagesink -e &
```

> Raspberry pi v2 (imx477):

No	width	height	framerate
0	3840	2160	30
1	1920	1080	60

```
$ gst-launch-1.0 -e nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM),width=3840,height=2160,framerate=30/1' ! queue ! nvvidconv ! fpsdisplaysink video-sink='xvimagesink' sync=false
```

```
$ gst-launch-1.0 -e nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM),width=1920,height=1080,framerate=60/1' ! queue ! nvvidconv ! fpsdisplaysink video-sink='xvimagesink' sync=false
```

Multiple:

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! "video/x-raw(memory:NVMM),width=1920,height=1080,framerate=60/1" ! nvvidconv ! xvimagesink -e & gst-launch-1.0 nvarguscamerasrc sensor-id=1 ! "video/x-raw(memory:NVMM),width=1920,height=1080,framerate=60/1" ! nvvidconv ! xvimagesink -e &
```

> IMX179 :

No	width	height	framerate
0	3280	2464	15
1	1920	1080	30
2	3280	1698	30
3	2096	1084	30
4	1640	1232	30
5	820	616	30
6	820	616	60

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)3280, height=(int)2464, format=(string)NV12, framerate=(fraction)15/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)1920, height=(int)1080, format=(string)NV12,
```

```
framerate=(fraction)30/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)3280, height=(int)1698, format=(string)NV12, framerate=(fraction)30/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)2096, height=(int)1084, format=(string)NV12, framerate=(fraction)30/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)1640, height=(int)1232, format=(string)NV12, framerate=(fraction)30/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)820, height=(int)616, format=(string)NV12, framerate=(fraction)30/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)820, height=(int)616, format=(string)NV12, framerate=(fraction)60/1' ! queue ! nvvidconv ! xvimagesink -e
```

> IMX290 :

No	width	height	framerate
0	1948	1096	30
1	1948	1096	60

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)1948, height=(int)1096, format=(string)NV12, framerate=(fraction)30/1' ! queue ! nvvidconv ! xvimagesink -e
```

```
$ gst-launch-1.0 nvarguscamerasrc sensor-id=0 ! 'video/x-raw(memory:NVMM), width=(int)1948, height=(int)1096, format=(string)NV12, framerate=(fraction)60/1' ! queue ! nvvidconv ! xvimagesink -e
```

> IMX290ISP :

No	width	height	framerate
0	1920	1080	25/30/50/60
1	1280	960	25/30/50/60
2	1280	720	25/30/50/60
0	800	600	25/30/50/60
1	640	480	25/30/50/60
2	640	360	25/30/50/60

```
$ gst-launch-1.0 v4l2src io-mode=4 device=/dev/video0 do-timestamp=true !  
'video/x-raw, width=1920, height=1080, framerate=60/1, format=UYVY' ! queue !  
xvimagesink sync=false
```

```
$ gst-launch-1.0 v4l2src io-mode=4 device=/dev/video0 do-timestamp=true !  
'video/x-raw, width=1280, height=960, framerate=30/1, format=UYVY' ! queue !  
xvimagesink sync=false
```

```
$ gst-launch-1.0 v4l2src io-mode=4 device=/dev/video0 do-timestamp=true !  
'video/x-raw, width=1280, height=720, framerate=30/1, format=UYVY' ! queue !  
xvimagesink sync=false
```

```
$ gst-launch-1.0 v4l2src io-mode=4 device=/dev/video0 do-timestamp=true !  
'video/x-raw, width=800, height=600, framerate=30/1, format=UYVY' ! queue !  
xvimagesink sync=false
```

```
$ gst-launch-1.0 v4l2src io-mode=4 device=/dev/video0 do-timestamp=true !  
'video/x-raw, width=640, height=480, framerate=30/1, format=UYVY' ! queue !  
xvimagesink sync=false
```

```
$ gst-launch-1.0 v4l2src io-mode=4 device=/dev/video0 do-timestamp=true !  
'video/x-raw, width=640, height=360, framerate=30/1, format=UYVY' ! queue !  
xvimagesink sync=false
```

7. GPIO usage

- For JetPack5.x
(1) Output: (e.g. gpio 398)

```
$ sudo su  
  
$ gpio_id=398  
$ sudo cat /sys/kernel/debug/gpio | grep ${gpio_id}  
# output:  
gpio-398 (PH.07      )  
$ gpio_index=PH.07  
$ echo ${gpio_id} > /sys/class/gpio/export  
$ echo out > /sys/class/gpio/${gpio_index}/direction  
$ echo 1 > /sys/class/gpio/${gpio_index}/value      # HIGH  
$ echo 0 > /sys/class/gpio/${gpio_index}/value      # LOW
```

(2) Input

```
$ sudo su
$ gpio_id=398
$ sudo cat /sys/kernel/debug/gpio | grep ${gpio_id}
# output:
  gpio-398 (PH.07          )
$ gpio_index=PH.07
$ echo ${gpio_id} > /sys/class/gpio/export
$ echo in > /sys/class/gpio/${gpio_index}/direction
$ cat /sys/class/gpio/${gpio_index}/value      # 1: HIGH,  0: LOW
```

(3) Disable

```
$ sudo su
$ gpio_id=398
$ echo ${gpio_id} > /sys/class/gpio/unexport
```

For L4T (Linux for Tegra) BSP support and the other software support associated with NVIDIA® Jetson Orin NX, please visit AVerMedia website to contact our technical support function. (<https://www.avermedia.com/tw/support/contact>)

8. Force Recovery Mode

USB 3.1/ Jetson platform port of D133ONB can be used to re-program NVIDIA® Jetson Orin NX by using the other host system running NVIDIA Jetpack, as the procedure described below.

1. Power off the system. Ensure the system power must be completely OFF, instead of staying in the suspend mode or the sleep mode.
2. Connect a USB cable from Jetson platform USB port to the other host system which will be used to re-program the new system file into NVIDIA® Jetson Orin NX.
3. Press and hold down Force Recovery Button and then power on the carrier board.
4. After three seconds, release Force Recovery Button.
5. NVIDIA® Orin NX will show up on the USB list of the host system as a new NVIDIA target device.

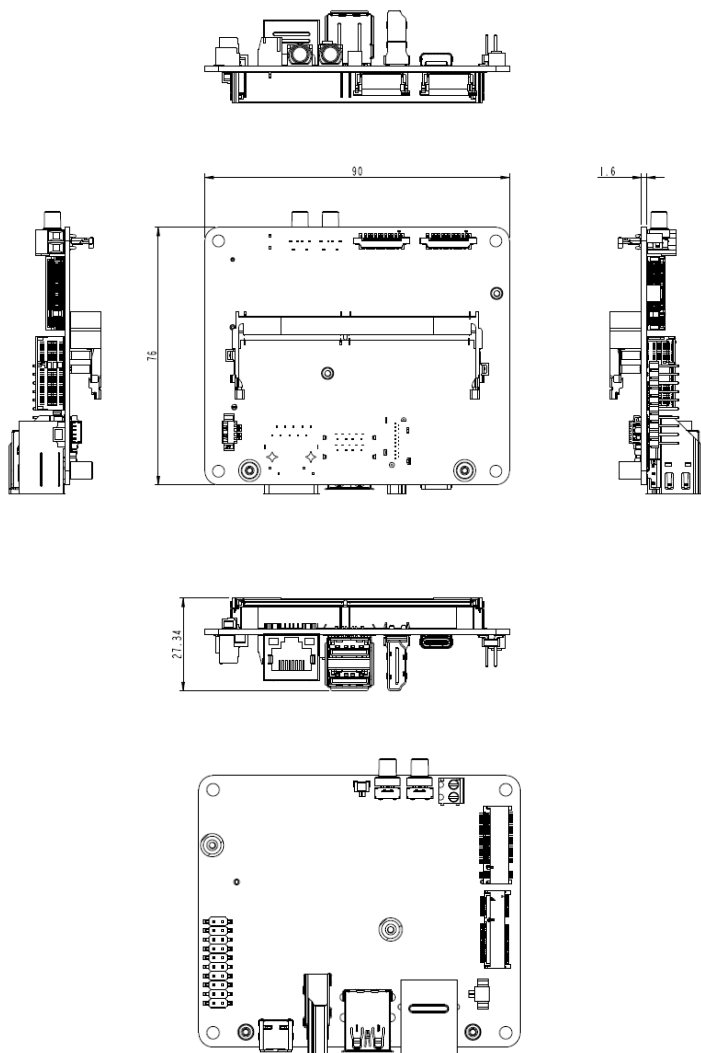
After the system software is updated successfully, please ensure to power off the system. A clean power-on will then revert Jetson platform port back to the host mode

9. Power Consumption

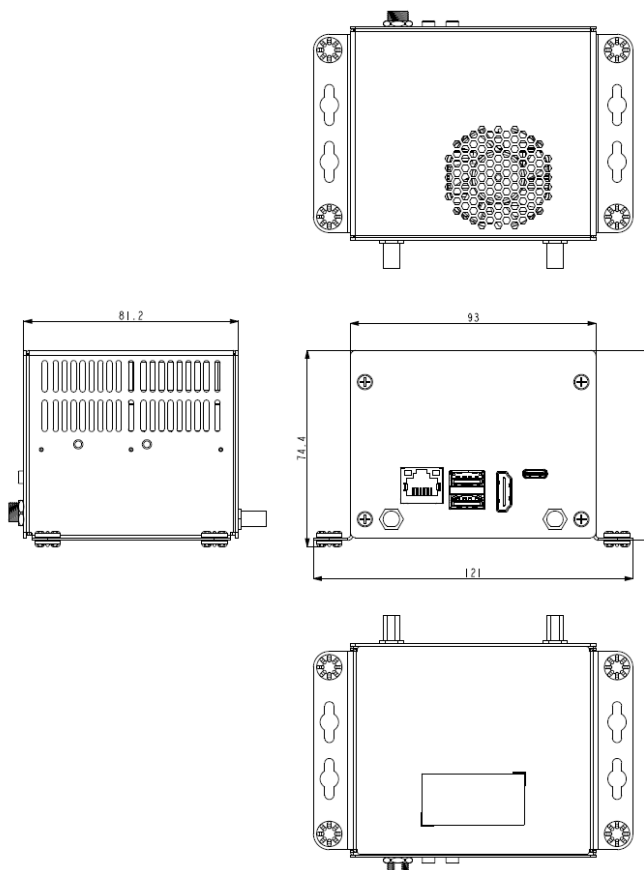
Item Description	Power Consumption
Theoretical	- D133ONB Power Consumption: 14.4W to 25.4W - D133OXB Power Consumption: 17.6W to 31.5W
Maximum System Power Consumption	The condition is connected to USB3.0*2, USB*1, MIPI *2, LAN *1, SSD 256G*1, Wifi 9260*1, HDMI*1, with CPU/ GPU full loading. (maximum power consumption up to 60W based on adapter)
Typical System Power Consumption	The power consumption under the normal operating mode is depending on the application software running with NVIDIA® Orin™ NX/Nano

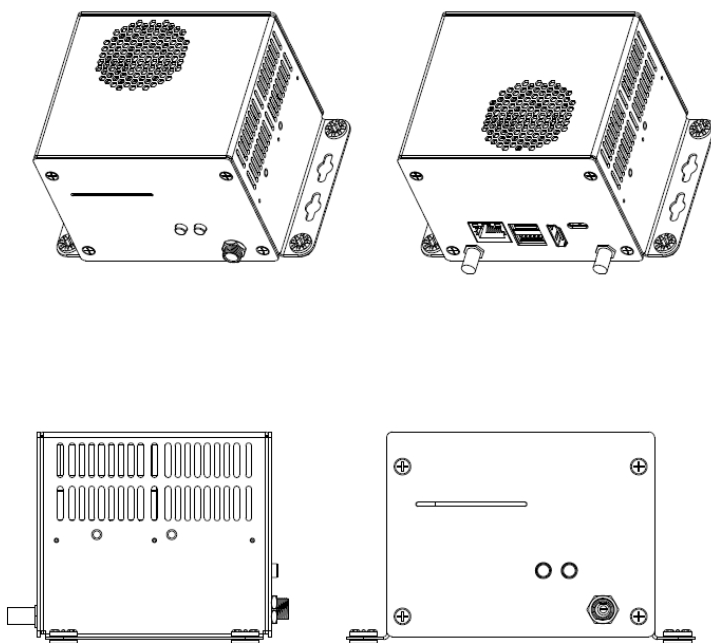
6.0 Dimension Drawings

6.1 Dimension Drawings of carrier board



6.2 Dimension Drawing of Box PC



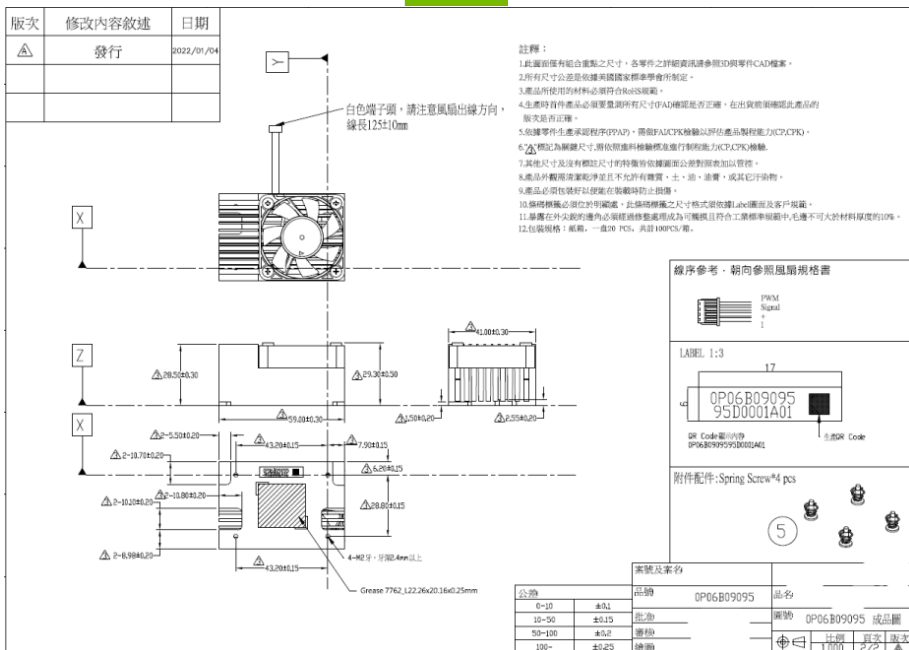


7.0 Accessory Drawings

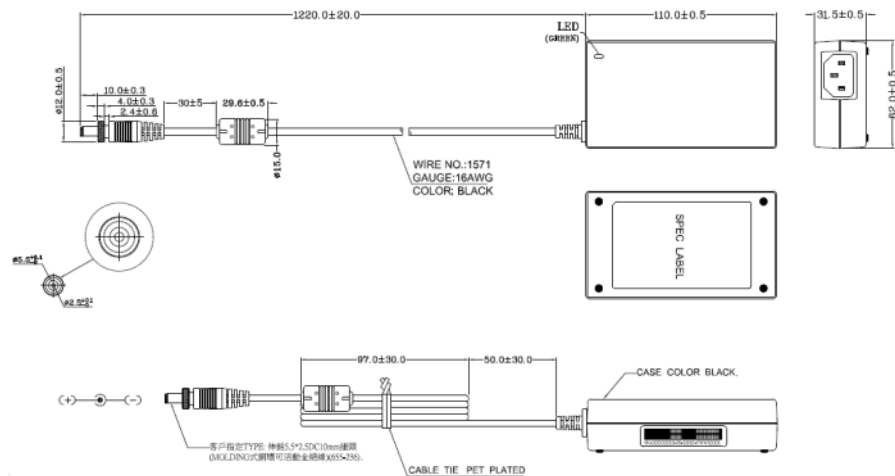
7.1 Fan Module/ Adapter/ Power Cord

Fan Module for Orin Nano

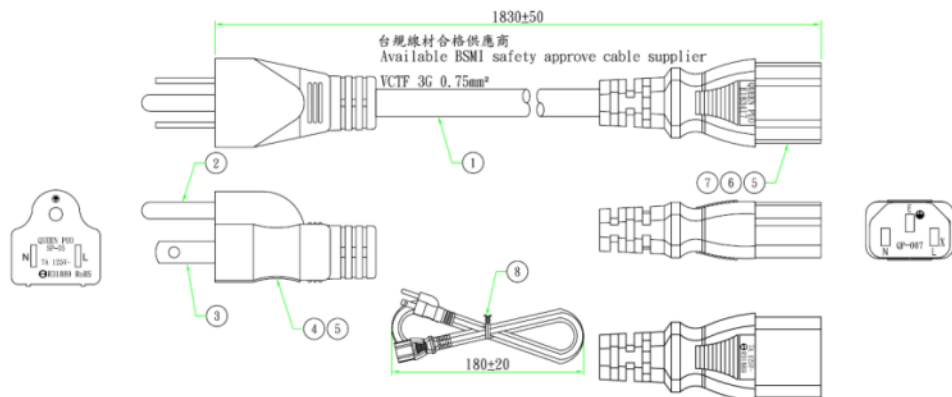
- Rated Voltage: 5V
- Operating Voltage Range: 3.5V~5.5V
- Rated Speed: 7000RPM±10%
(Testing Speed After Continuous 3 Minute Operation At Ambient Temperature Of 25℃)
- Life Expectancy: 70,000hours at 40℃ (WITH 15~65% RH)
- Bearing Type: Two Ball



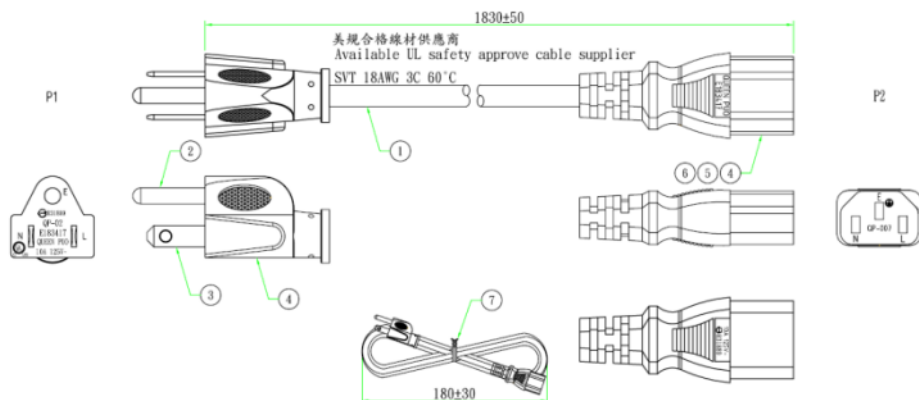
Power Adapter 04131HGOUANK



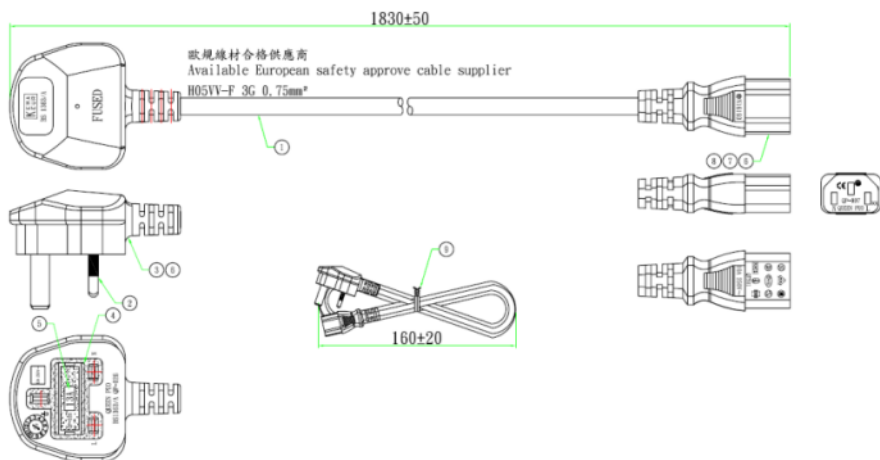
064APOWBRX-IPD (TW version)



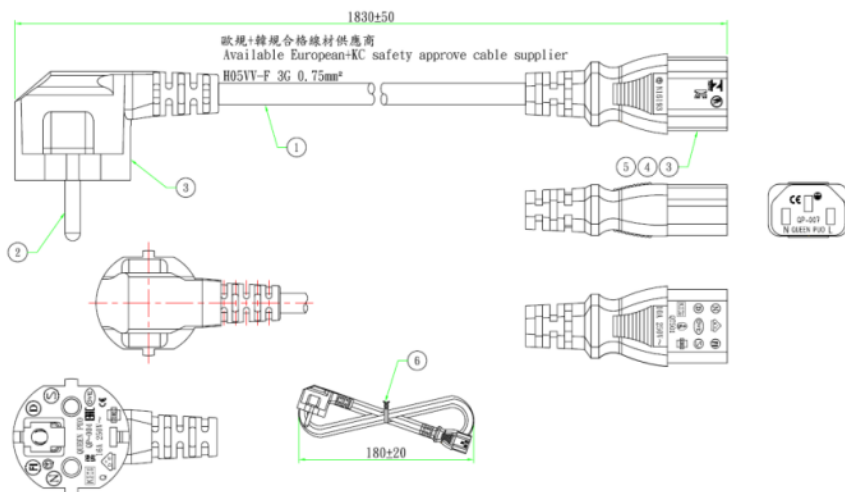
064APOWBR2-IPD (US version)



064APOWBRW-IPD (UK version)

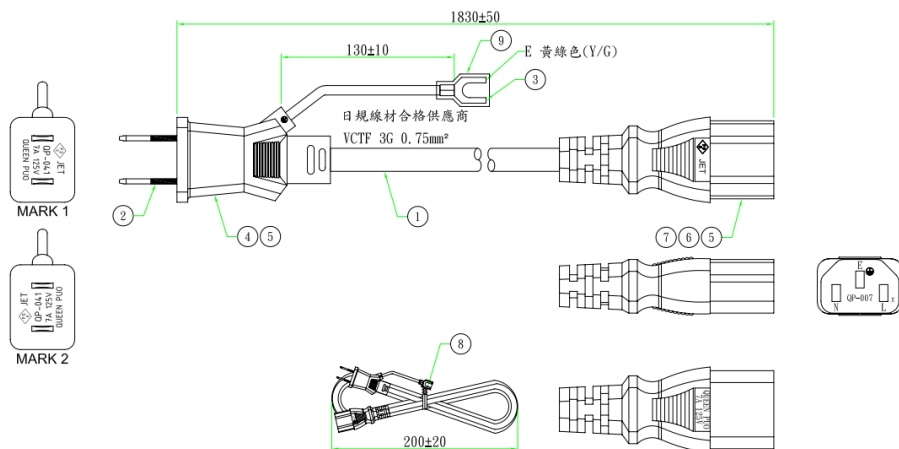


064APOWBR5-IPD (EU version)

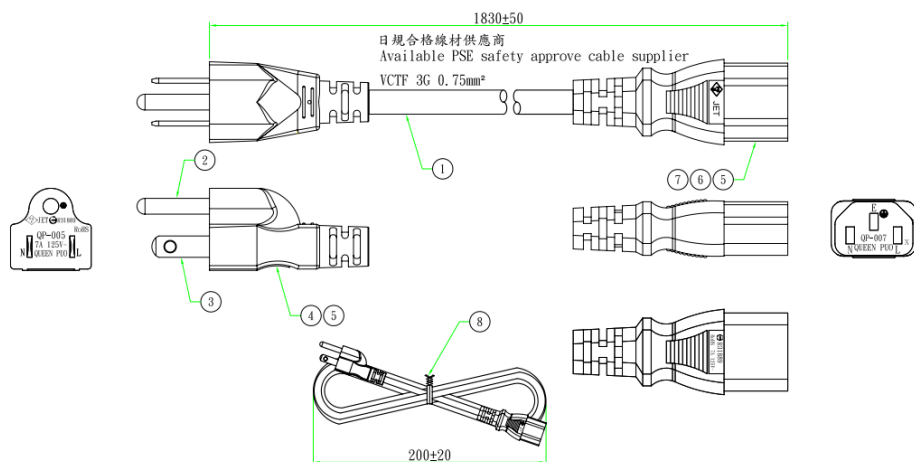


064APOWERRB32 (JP version, 2-pin with GND)

Warning : Indicating that the ground (GND) must be properly connected when plugging in the adapter.



064APOWERRB3X (JP version, 3-pin)



064APOWBR4-IPD (CN version)

